

Lexium integrated drives

IL●1 for CANopen, PROFIBUS DP, RS 485
ILA1 with AC synchronous servo motor

References												
Example:	I	L	A	1	B	5	7	1	P	B	1	A
Motor type A = AC synchronous servo motor	I	L	A	1	B	5	7	1	P	B	1	A
Supply voltage 1 = 24 ... 36 V	I	L	A	1	B	5	7	1	P	B	1	A
Communication interface B = PROFIBUS DP F = CANopen DS301 R = RS 485	I	L	A	1	B	5	7	1	P	B	1	A
Flange size 57 = 57 mm	I	L	A	1	B	5	7	1	P	B	1	A
Motor length ("L") (1) 1 = motor length ("L") 2 = motor length ("L")	I	L	A	1	B	5	7	1	P	B	1	A
Winding type P = medium speed of rotation, medium torque T = high speed of rotation, medium torque	I	L	A	1	B	5	7	1	P	B	1	A
Connection technology B = printed circuit board connector C = industrial connector	I	L	A	1	B	5	7	1	P	B	1	A
Measurement system 1 = singleturn encoder 2 = multiturn encoder (2)	I	L	A	1	B	5	7	1	P	B	1	A
Holding brake A = no holding brake F = with holding brake (2)	I	L	A	1	B	5	7	1	P	B	1	A

(1) The motor length "L" depends on the mechanical characteristics, see pages 4/19 and 4/21.
(2) Holding brake and multiturn encoder cannot be used in combination.