

Lexium integrated drives

IL●2 for DeviceNet, EtherCAT, Modbus TCP,
Ethernet Powerlink
ILS2 with 3-phase stepper motor

References												
Example:	I	L	S	2	D	5	7	1	P	B	1	A
Motor type S = 3-phase stepper motor	I	L	S	2	D	5	7	1	P	B	1	A
Supply voltage 2 = 24 ... 48 V	I	L	S	2	D	5	7	1	P	B	1	A
Communication interface D = DeviceNet E = EtherCAT P = Ethernet Powerlink T = Modbus TCP	I	L	S	2	D	5	7	1	P	B	1	A
Flange size 57 = 57 mm 85 = 85 mm	I	L	S	2	D	5	7	1	P	B	1	A
Motor length ("L") (1) 1 = motor length ("L") 2 = motor length ("L") 3 = motor length ("L")	I	L	S	2	D	5	7	1	P	B	1	A
Winding type P = medium speed of rotation, medium torque T = high speed of rotation, medium torque (2)	I	L	S	2	D	5	7	1	P	B	1	A
Connection technology B = printed circuit board connector C = industrial connector	I	L	S	2	D	5	7	1	P	B	1	A
Measurement system 1 = index pulse	I	L	S	2	D	5	7	1	P	B	1	A
Holding brake A = no holding brake F = with holding brake	I	L	S	2	D	5	7	1	P	B	1	A

(1) The motor length "L" depends on the mechanical characteristics, see pages 4/65, 4/68 and 4/69.

(2) Winding type T only with ILS2●853.

(3) Holding brake only with ILS2●85.