

BRH 3 Phase Servo Motors

	1	2	3	4	5	6	7	8	9	10	11	12	13
	root			characteristic									
	B	R	H	X	X	X	X	X	X	X	X	X	X
Example:	B	R	H	0	5	7	3	P	0	0	A	2	A
Servo Motor												Mechanical interface - mount standard A - international IEC standard	
Motor frame size											Electrical interface 1 - straight connector - coninvers 2 - right angular, turnable connector - coninvers		
057 - 57 mm flange size 085 - 85 mm flange size 110 - 110 mm flange size											Brake A - without brake F - with brake		
Motor stack											Feedback encoder 0 - Absolute SinCos Single Turn (16 lines per rotation) - SEK 52 <i>SEK52 is LXM05 compatible. LXM32 drives don't support this encoder type !!!</i> 1 - Absolute SinCos Single Turn (128 lines per rotation) - SKS 36 SKS36 is LXM05 & LXM32 compatible! 2 - Absolute SinCos Multi Turn (128 lines per rotation) - SKM 36 SKM36 is LXM05 & LXM32 compatible!		
1 - one stack 2 - two stacks 3 - three stacks 4 - four stacks (not available for BRH110)													
Winding Identification													
M - max.torque - (this winding is defined for BRH085x, for bundles with 1~ LXM05) P - Medium speed - (Standard) T - max.speed - (this winding is defined for BRH0571).													
Mechanical interface - shaft & protection													
0 - smooth shaft / protection class: shaft IP 40; housing IP 56 1 - keyed shaft / protection class: shaft IP 40 ; housing IP 56 2 - smooth shaft / protection class shaft & housing IP 56 3 - keyed shaft / protection class: shaft & housing IP56													



Note: This is a typecode - You can order with this code.

